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CHAPTER 2. Discrete-Time Signals and Systems 11 5. (a) Proof: If the sinusoidal signal $\cos(\omega_0 n + \theta_0)$ is periodic in n , we need to find a period N that satisfy $\cos(\omega_0 n + \theta_0) = \cos(\omega_0 n + \omega_0 N + \theta_0)$ for every n . Since ω_0 , $\omega_0 N = 2\pi$ is a rational number, we can substitute $\omega_0 = \frac{2\pi M}{N}$ into the previous periodic condition to have $\cos(2\pi M n / N + \theta_0) = \cos(2\pi M n / N + 2\pi M + \theta_0)$...

Discrete-Time Signals and Systems - Solutions Manual

First, digital computers are, by design, discrete-time devices, so discrete-time signals and systems includes digital computers. Second, almost all the important ideas in discrete-time systems apply equally to continuous-time systems. Alas, even discrete-time systems are too diverse for one method of analysis.

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A discrete-time system is a device or algorithm that, according to some well-defined rule, operates on a discrete-time signal called the input signal or excitation to produce another discrete-time signal called the output signal or response. Mathematically speaking, a system is also a function.

Discrete-time signals and systems

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Signal-processing systems may be classified along the same lines as signals. That is, continuous-time systems are systems for which both the input and the output are continuous-time signals, and discrete-time systems are those for which both the input and the output are discrete-time signals. Similarly, a digital system is a system for which

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The WGM resonances shifted as a function of the refractive index of the analyte solution, ... 610
9.5.7 Frequency analysis of signals and systems in the discrete time domain ...

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Discrete-Time Signals and Systems Z. Aliyazicioglu Electrical and Computer Engineering Department Cal Poly Pomona ECE 308 -6 ECE 308-6 2 Analysis of Linear Time Invariant Systems (LTI) Introduction Two basic methods for analyzing the response of LTI: • The direct solution of the input-output equation for the linear system

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Chapter 2: Discrete-Time Signals and Systems Discrete-Time Signals and Systems Reference: Sections 2.1 - 2.5 of John G. Proakis and Dimitris G. Manolakis, Digital Signal Processing: Principles, Algorithms, and Applications, 4th edition, 2007. Dr. Deepa Kundur (University of Toronto) Discrete-Time Signals and Systems 2 / 36 Chapter 2: Discrete ...

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Aly El Gamal ECE 301: Signals and Systems Homework Solution #1 Problem 3 Problem 3 A discrete-time signal $x[n]$ is shown in Figure 3. Sketch and label carefully each of the following signals: (a) $x[3n]$ (b) $x[n]u[3n]$ (c) $x[n-2]$ Figure 3: The discrete-time signal $x[n]$. Solution Figure 4: Sketches for the resulting signals. 4

ECE 301: Signals and Systems Homework Solution #1

5.3. Discrete-Time Impulse Response 5.3.1. Definition of Discrete-Time Impulse Response A linear time-invariant discrete-time system can be described by the discrete-time impulse response, which is defined as the response of the system to the impulse sequence $\delta[n]$. 0, otherwise a, 0 $n \geq 6$ and $x(n) = 0$ otherwise 1, 0 $n \leq 4$ (3) $x(n) = 1$ 2

5. Time-Domain Analysis of Discrete-Time Signals and Systems

Determine if this discrete-time signal has finite energy, finite power and compare these characteristics with those of the continuous-time signal $x(t)$ when $\Omega_0 = \pi$ and when $\Omega_0 = 3.2$ rad/s (an upper approximation of π). Solution. The continuous-time signal $x(t)$ has infinite energy, and so does the discrete-time signal $x[n]$, for both values ...

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