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Mark A. Haidekker, in Linear Feedback Controls, 2013. 11.7 Frequency Response of Digital Filters. In Chapters 4 and 9 Chapter 4 Chapter 9 we have introduced an interpretation of time-discrete control systems as digital filters. Both time-discrete feedback controls and digital filters are described by their z-transform transfer functions.If a time-discrete system with the transfer function $H(z)$...

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Systems governed by difference equations are the subject of a companion paper. II - Discrete-Time Systems-The second method of Lyapunov is applied to the study of discrete-time (sampled-data) systems. With minor variations, the discussion parallels that of the companion paper on continuous-time systems.

Control system analysis and design via the second method ...

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The time interval between two discrete instants is taken to be sufficiently short that the data for the time between them can be approximated by simple interpolation. Discrete-time control systems differ from continuous-time control systems in that signals for a discrete-time control system are in sampled-data form or in digital form.

Discrete time control systems - SlideShare

A comprehensive treatment of the analysis and design of discrete-time control systems which provides a gradual development of the theory by emphasizing basic concepts and avoiding highly mathematical arguments. The book features comprehensive treatment of pole placement, state observer design, and quadratic optimal control.

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Discrete Time Control Systems 2nd Ogata

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The asynchronous containment control problem of second-order discrete-time multi-agent systems with time-varying delays is investigated. Asynchrony in this paper means that each agent updates state information via its clock that is independent of those of the other agents', and the time sequence over which each agent updates its state information is not necessarily equispaced.

Asynchronous containment control for discrete-time second ...

Discrete control systems, as considered here, refer to the control theory of discrete-time Lagrangian or Hamiltonian systems. Thesediscrete-time models are based on a discrete variational principle , and are part of the broader field of geometric integration .

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